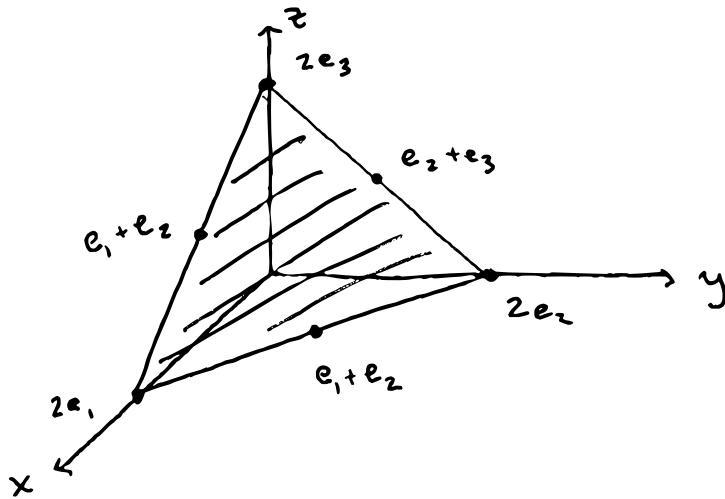


Consider \mathbb{Z}_4 acting on coordinates of \mathbb{R}^4 by permutation.

The convex hull of the orbit of $(1,1,0,0)$ defines a shape. What is it?

All points live in the hyperplane $\{x+y+z+w=2\}$ so we may project into \mathbb{R}^3 .

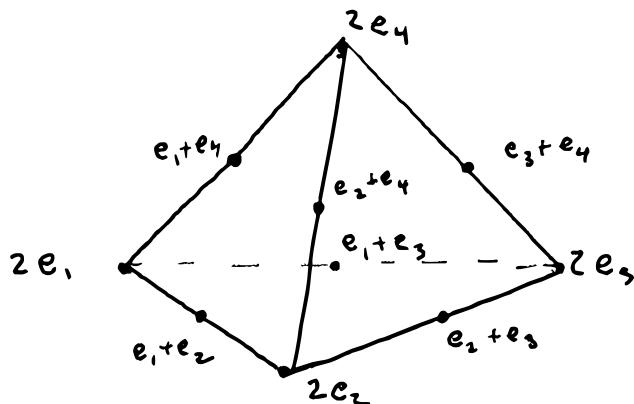
By analogy, we first consider a lower dimensional space. For a moment consider $\{x+y+z=2\} \subseteq \mathbb{R}^3$. This intersects the positive quadrant in a simplex.



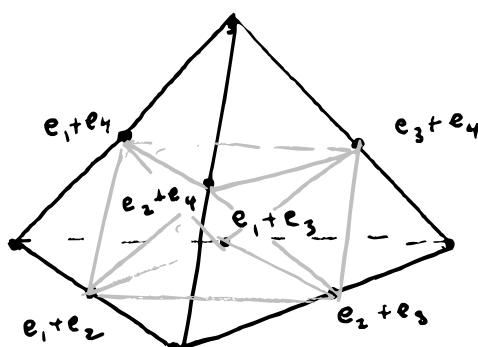
Now consider the points $(1,1,0)$, $(1,0,1)$, and $(0,1,1)$ they are $2e_1 + e_2$, $e_1 + e_3$, and $e_2 + e_3$.

The point of this analogy is to give intuition for the \mathbb{R}^4 case.

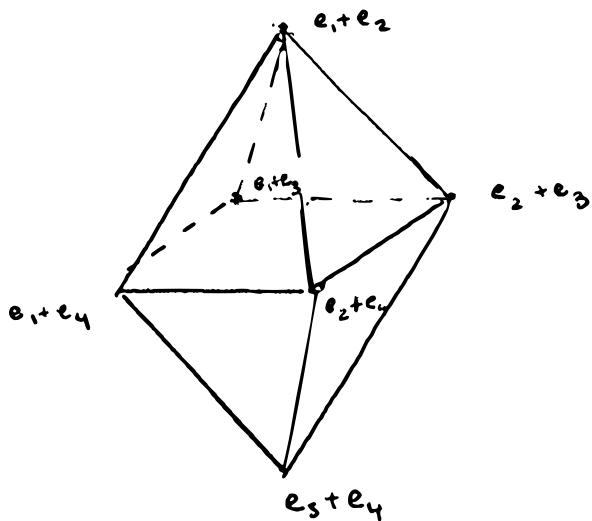
As previously stated, the points live in the hyperplane $\{x+y+z+w=2\}$. Notice that since the shape we consider is the orbit of a point with non-negative coordinates, we may restrict our attention to the intersection of the hyperplane with the positive orthant. As before this intersection is a simplex:



Now note that $(1,1,0,0) = e_1 + e_2$ and so the orbit of the point is all $e_i + e_j$ where $i \neq j$. These points are drawn below.



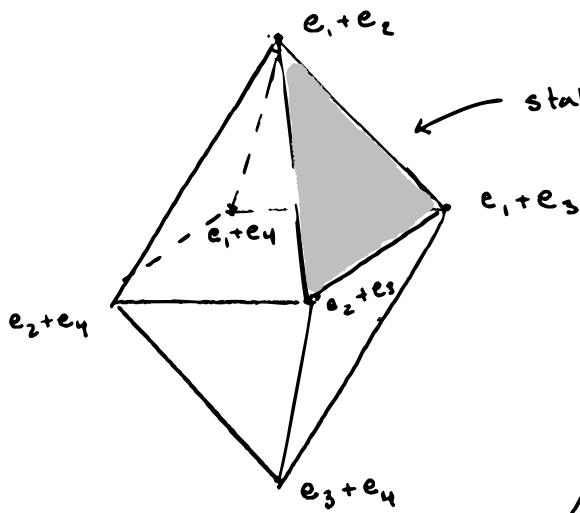
Renaming the simplex we see that the shape is an octahedron.



Now, the action of S_4 on the vertices induces an action on the faces. The action is a permutation representation on each orbit. There are two distinct orbits, each of which consists of a checkerboard pattern of faces, which can be seen on the next page. The permutation representation carried by a single orbit can be found by induction the trivial representation on the stabilizer of a single face:

$$\text{Ind}_{S_3 \times S_1}^{S_4} (\mathbb{1}_{S_3 \times S_1}).$$

The trivial representation $\mathbb{1}_{S_3 \times S_1}$ may be written as the tensor product $\mathbb{1}_{S_3} \otimes \mathbb{1}_{S_1}$. The induction corresponds to multiplication of Schur functions: $s_{\lambda} \cdot s_{\mu} = s_{\lambda} + s_{\mu}$. Since there are two distinct orbits, and the stabilizer of any face is isomorphic to $S_3 \times S_1$, the repn is $(V^4 \otimes V^{3,1})^{\oplus 2}$.



stabilized by $\tilde{G}_{\{1,2,3\}} \times \tilde{G}_4$

